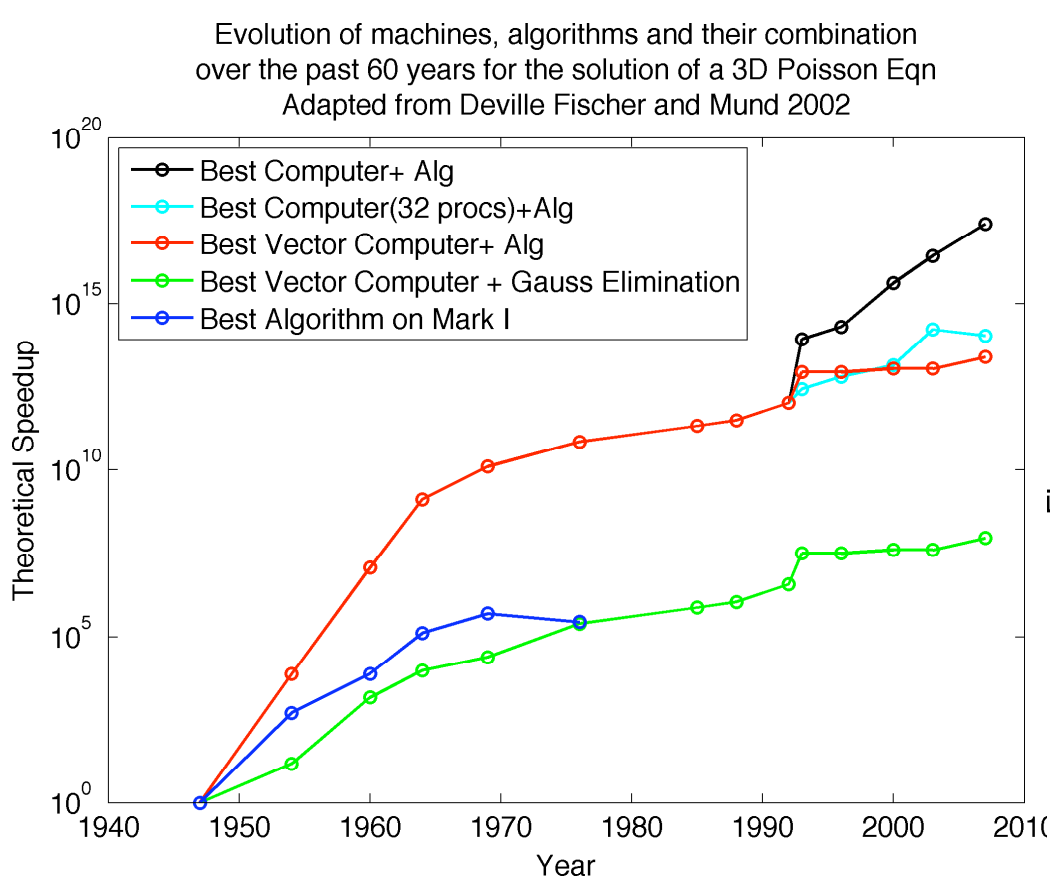


Fast Iterative Solvers for Fluid Flows

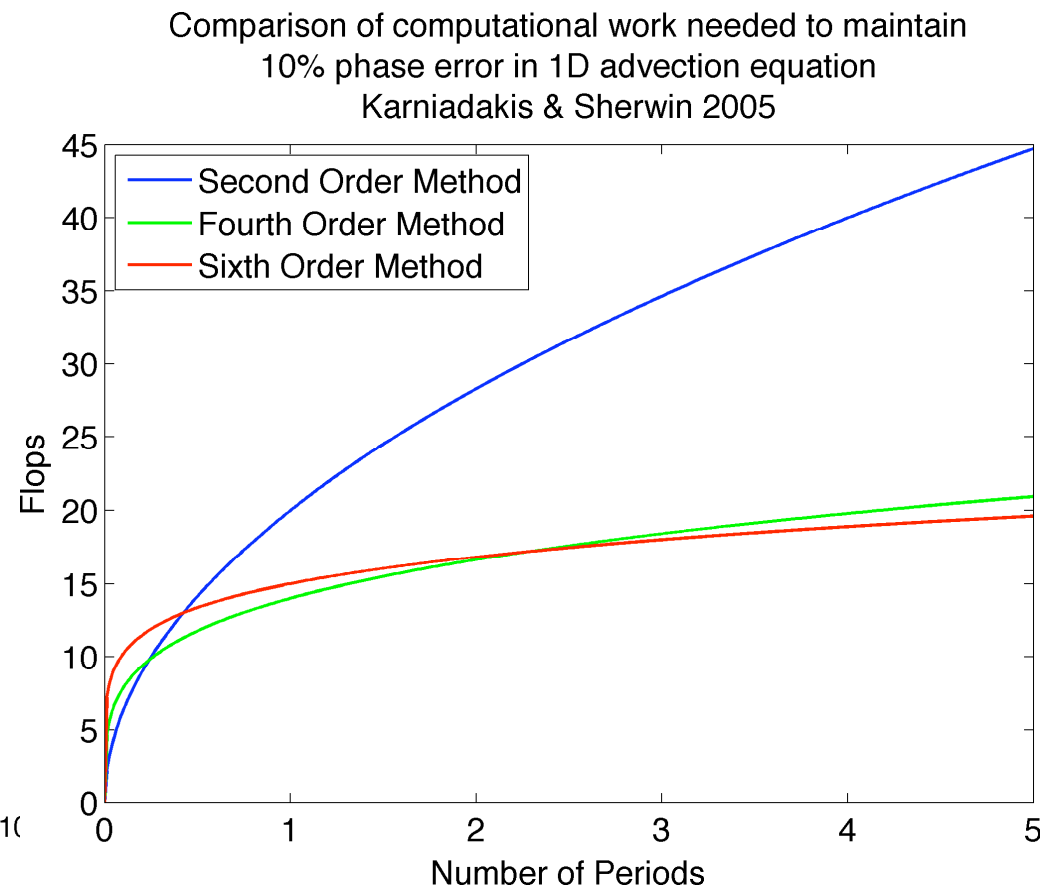
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Motivation - Efficient Solvers & Discretization

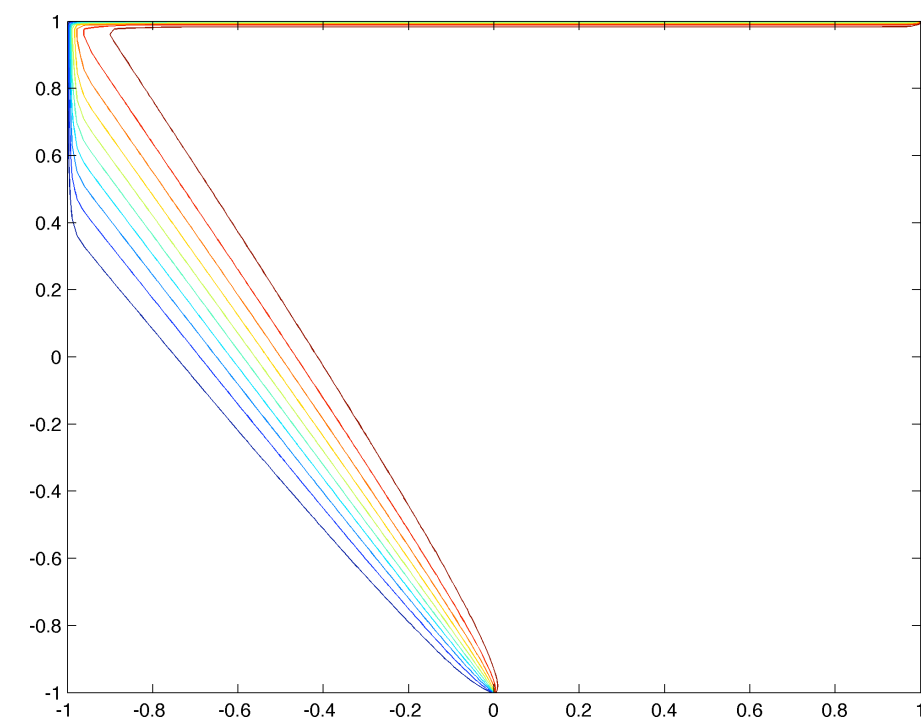
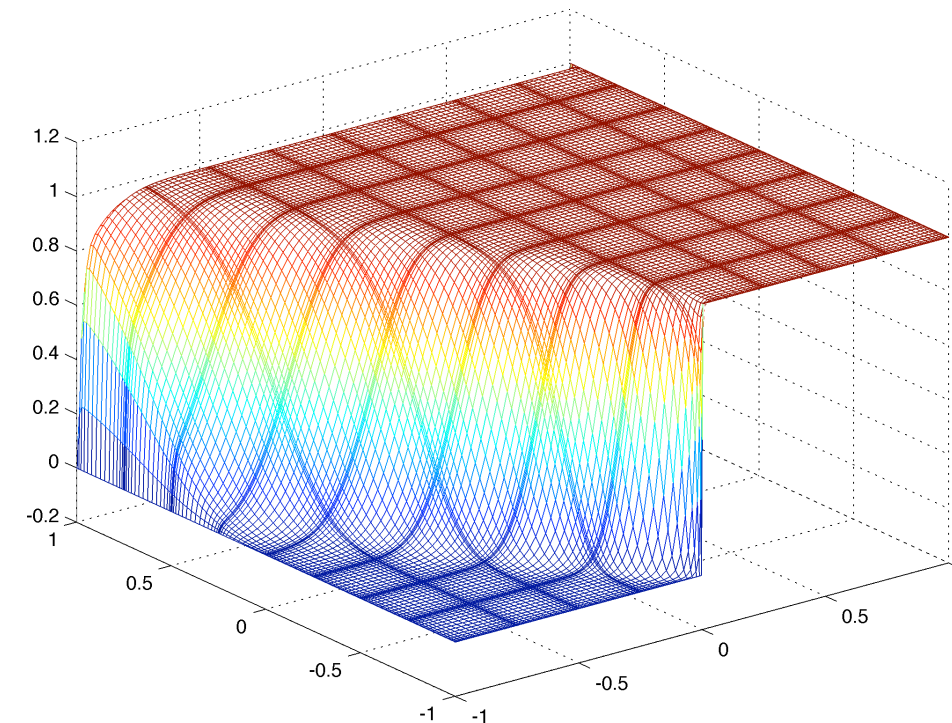


Faster machines and computational algorithms can dramatically reduce simulation time.



High order based discretizations can be used to obtain accurate, efficient simulations.

Solver Results - Bi-constant Wind



Solution and contour plots of a steady advection-diffusion flow with bi-constant wind using Domain Decomposition & Fast Diagonalization. $Pc=200$. Interface solve takes 150 steps to obtain 10^{-5} accuracy.

Model - Steady Advection Diffusion

$$-\epsilon \nabla^2 u + (\vec{w} \cdot \nabla) u = f$$

Inertial and viscous forces occur on disparate scales causing **sharp flow features** which:

- require fine numerical grid resolution
- cause poorly conditioned systems.

These properties make solving the discrete systems computationally expensive.

Methods - Spectral Element Discretization

A spectral element discretization provides:

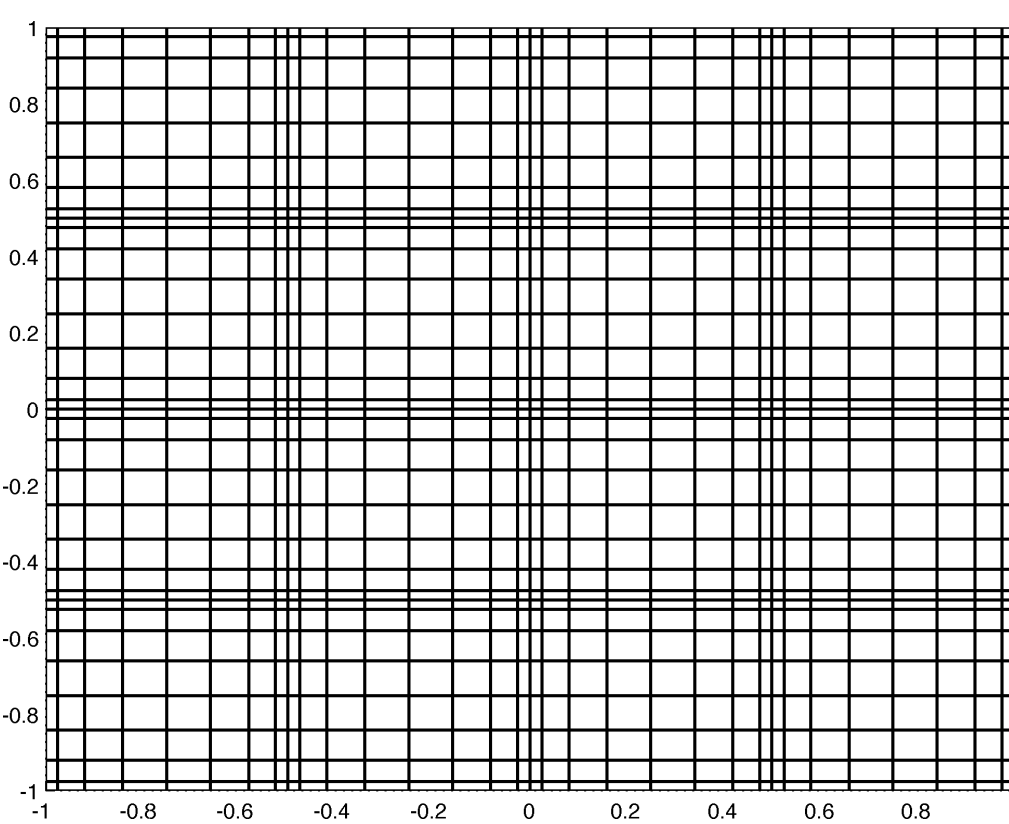
- **accurate element based discretization**
- **large volume to surface ratio**

For bi-constant winds, we can use:

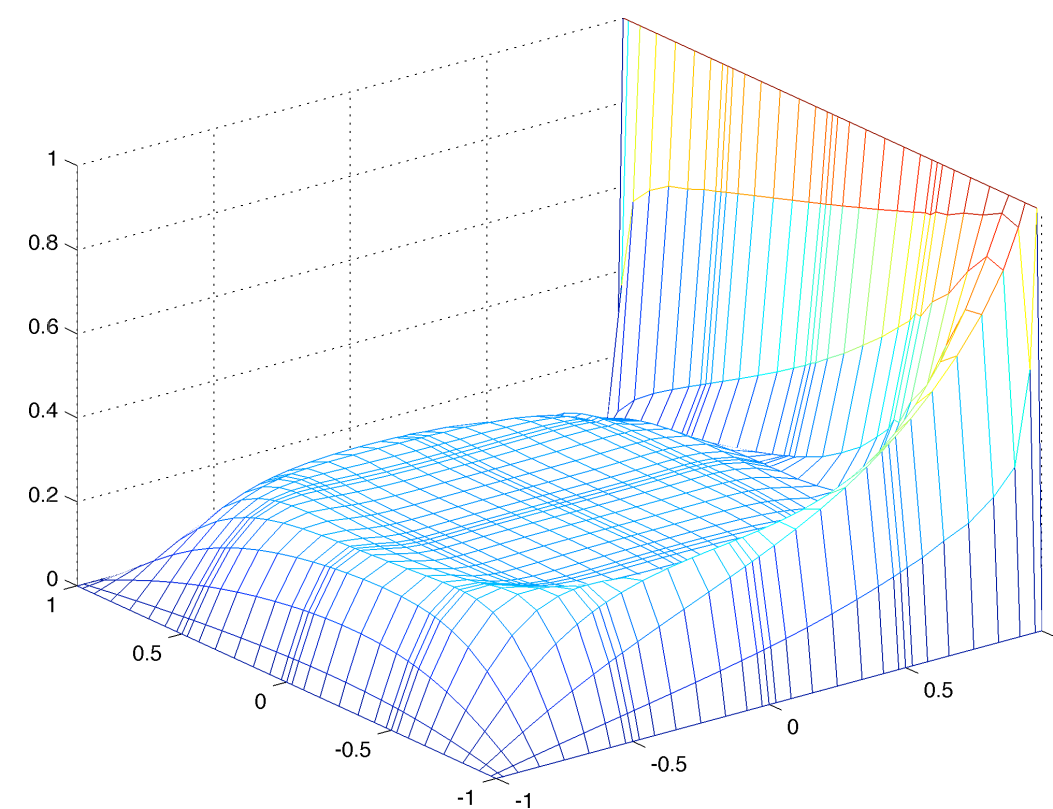
- **fast diagonalization**
- **minimal memory**

$$F(\vec{w})u = Mf$$

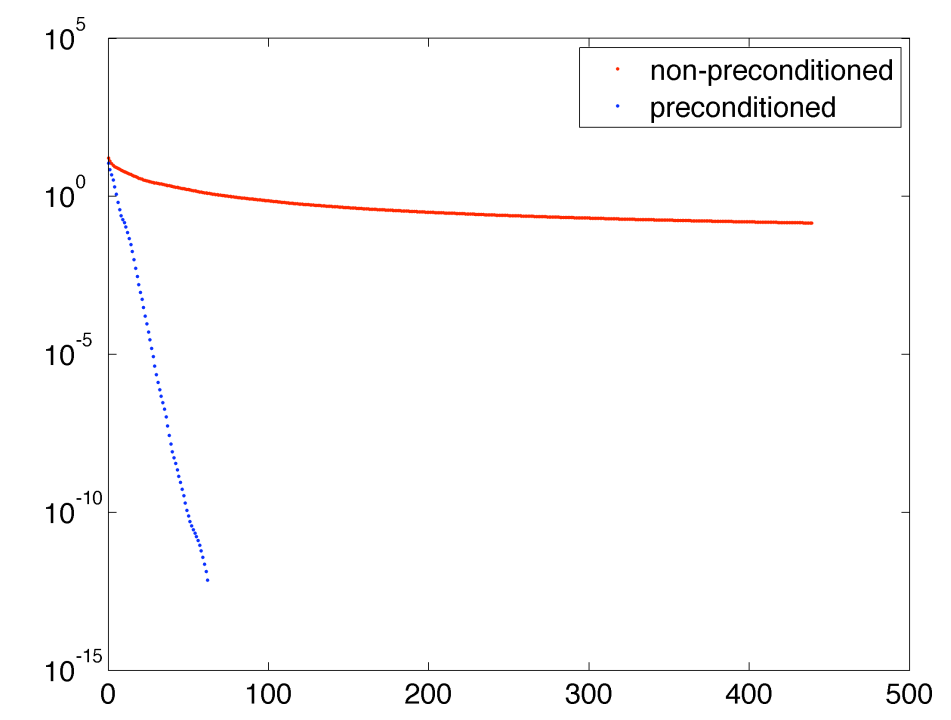
$$\tilde{F} = \hat{M} \otimes \hat{F}(w_x) + \hat{F}(w_y) \otimes \hat{M}$$



Preconditioner Results - Recirculating Wind



Steady advection-diffusion flow with recirculating wind. $Pc=200$. Hot plate at wall results in sharp internal boundary layer.



Comparison of iteration residuals.
• 10 interface steps yield 10% accuracy
• $(P+1)[40N+(P+1)]$ additional flops per step

Future Directions

- Precondition Interface Solve
- 2D & 3D **Navier-Stokes**
- Flows with boundary layers

Methods - Solver & Preconditioner

The discrete system of equations is solved iteratively using Flexible GMRES.

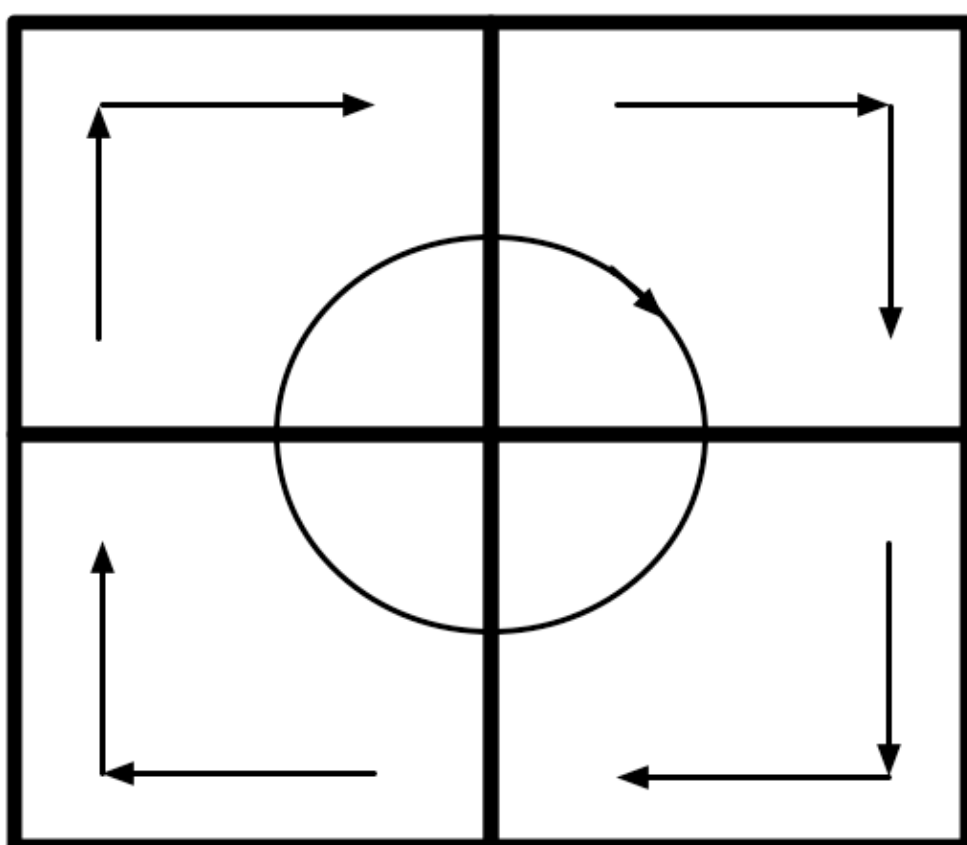
We construct a **preconditioner** based on:

- **Bi-constant wind approximations**
- **Fast Diagonalization**
- **Domain Decomposition**

$$F(\vec{w})P_F^{-1}P_F u = Mf$$

$$P_F^{-1} = R_0^T \tilde{F}_0^{-1}(\bar{w}_0)R_0 + \sum_{e=1}^N R_e^T \tilde{F}_e^{-1}(\bar{w}_e)R_e$$

$$\tilde{F}_e^{-1} = (\hat{M}^{-1/2} \otimes \hat{M}^{-1/2})(S \otimes T)(\Lambda \otimes I + I \otimes V)^{-1}(S^{-1} \otimes T^{-1})(\hat{M}^{-1/2} \otimes \hat{M}^{-1/2})$$



References

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H. Elman, D. Silvester, & A. Wathen, Finite Elements and Fast Iterative Solvers with applications in incompressible fluid dynamics, Numerical Mathematics and Scientific Computation, Oxford University Press, New York, 2005.

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